



C5 Two State Model - Maple 7 **Fully Analytical approach**

Simulator: Maple 7 is a computer algebra system which is mainly used for symbolic calculation but it also includes numerical features. It provides a vast library of built-in functions and operations and allows arbitrary high accuracy by making it possible to change the numbers of digits carried in floats.

Model: This solution doesn't use Maple's integrated ODE solver dsolve (although possible): it shows how one can implement an algorithm for solving a system of differential equations. First the eigenvalues and the eigenvectors of the linear homogeneous system of equations are determined, to create a solution basis for the homogeneous system. Therefore Maple's function Eigenvals is used.

```
> A:=matrix([[-c1,c1],[0,-c3]]);
> b_1:=matrix(2,1,[c1*c2_1,c3*c4_1]);
> b_2:=matrix(2,1,[c1*c2_2,c3*c4_2]);
   lambda:=evalf(Eigenvals(A, vecs));
> J:=array([[exp(lambda[1]*t),0],
                  [0,exp(lambda[2]*t)]]);
> L:=multiply(vecs,J);
```

Next the inhomogeneous part is solved by a simple system of equations because the inhomogenity is constant. (The Matrix doesn't have to be inverted).

```
const1:=solve({A[1,1]*k1_1+A[1,2]*k2_1=b_1[1,1]
A[2,1]*k1_1+k2,2]*k2_1=b_1[2,1], {k1_1,k2_1};

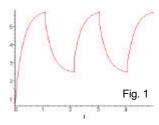
> const2:=solve({A[1,1]*k1_2+A[1,2]*k2_2=b_2[1,1],
    A[2,1]*k1_2+A[2,2]*k2_2=b_2[2,1], {k1_2,k2_2});
> Eq:=geneqns(L,[v1,v2],
               vector([y1 init+k1 1,y2 init+k2 1]));
> Eqt:=subs(t=t_init,Eq);
> lsg1:=solve(Eqt, {v1, v2});
> Eq:=geneqns(L,[v1,v2],
               vector([y1_init+k1_2,y2_init+k2_2]));
> Eqt:=subs(t=t init,Eq);
> lsg2:=solve(Eqt, {v1, v2});
  t_init:=0; y1_init:=4.2; y2_init:=0.3;
> z:=0; i:=0; state:=1;
```

The time instants of the change of states are determined by a modified bisection method, whereby the smallest step size can be constituted.

```
> while (z<5) do i:=i+1;
  sol:=multiply(L, matrix(2,1,[v1,v2])):
 \label{funcy1||i:=unapply(sol[1,1]-k1_||state,t):} funcy1||i:=unapply(sol[1,1]-k1_||state,t):
 funcy2||i:=unapply(sol[2,1]-k2_||state,t):
step:=0.01;
 if state = 1 then
    while step>=step_bound do
      while ((funcy1||i(z)<5.8) and (z<5)) do
        z:=z+step;
      end do;
      z:=z-step;
      step:=step/10;
   end do; else ..
 z:=z+step*10; disc||i:=z;
 state:=(state mod 2)+1; t_init:=z;
y1_init:=funcy1||i(z); y2_init:=funcy2||i(z);
end do:
```

Results Task a: Simulation in time domainswitching times and final value. The table at the right shows the time points for all detected discontinuities and also the value of $y_1(5)$. The associated graph of y_1 is shown in Fig. 1. The result was calculated with Digits: =15 and a step_bound of 10

t ₁	1.10830616780000
t ₂	2.12968535520000
t ₃	3.05415290710000
t ₄	4.07553209450000
t ₅	4.99999964640000
y ₁ (5)	5.36944281876193

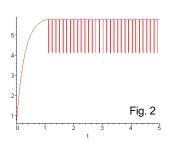


Task b: Influence of accuracy on solution. The model accuracy can be varied by two parameters. First by changing the number of digits of the used floating-point numbers (Maple's environment variable Second by the variable step bound, Digits.) which determines the minimum step size for the time loop. In the next table the results for different values of these parameters are shown. Because there are nearly no differences between values by changing Digits (Digits = 30 used), only the step bound is varied

step	y ₁ (5)	Time of last discontinuity
10 ⁻⁶	5.79999908287093882 550066486064	4.075535
10 ⁻¹⁰	5.36944281876190194 324447677610	4.9999996464
10 ⁻¹⁴	5.36931214700633035 514320327281	4.99999964622034

With a step size of 10⁻⁶ one discontinuity less is found.

Task d: Highly oscillating tion. Figure 2 shows the graph of y₁ for system with changed state 2 parameter values. It's high frequently oscillating and forces 62 discontinuities. The first and last discontinuities (see table at right) are computed with following accuracy



t1	1.10830616777114
t2	1.12172996789144
	• • •
t61	4.92304010708071

parameters: step_bound:=10⁻¹⁴ Digits:=20

The final value of y₁ is 5.7804025205614051443.

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