Exploring the Advantages of Multi-Method Modelling in the Use Case of a Large Socio-Technical Infrastructure System: **The Airport City**

Barbara Glock^{1*}, Niki Popper¹, Felix Breitenecker²

¹dwh GmbH, dwh Simulation Services, Neustiftgasse 57-59, 1070 Vienna, Austria; **barbara.glock@dwh.at* ²Institute for Analysis and Scientific Computing, Vienna University of Technology, Wiedner Haupstraße 8-10, 1040 Vienna, Austria;

Simulation Notes Europe SNE 26(3), 2016, 175 - 182 DOI: 10.11128/sne.26.tn.10347 Received: June 17, 2016; Revised: July 10, 2016; Accepted: July 15, 2016;

Abstract. Modelling large socio-technical infrastructure systems tends to be tricky. In the past either one 'best fitting' modelling technique was used to model the system or a small part of the system was modelled. This lead to many tradeoffs, where the chosen modelling method got to its limits: by modelling a small part, effects from outside were ignored and modelling the whole system with one method lead to either much detail where micro-based methods were applied - where it was not required which further lead to high computation times. Using a macro-based approach lead to less detail where it would have been needed. Different parts of the Airport City are modelled with the best fitting modelling technique. These parts are researched for their coupling mechanisms to model the whole system and see how effects in one part evolve and pass to the next subsystem. An agent based model of the landside with a modal split of passenger arrival, a Discrete Events terminal model, a multi-method agent-based model with an integrated System Dynamics model representing the retail area of an airport and an agent based model of the airside are developed and their advantages and disadvantages are being explored.

Introduction

The planning of big infrastructure developments is getting more challenging due to more complex structures and an increased number of construction standards. Large infrastructure systems can be decomposed into subsystems that are somehow interconnected and correspond on different levels with each other.

This makes an analysis more difficult. Furthermore, there are different views on the system that need to be addressed and satisfied: stakeholders, planners, consumers, decision makers, etc. On the one side questions addressing profit arise, and on the other side consumers want a specific level of quality. Also ecologic aspects need to be kept in mind. In general this calls for modelling and simulation. These large systems, broken into pieces, consist of different subsystems with much more detail, each of them with its own dynamic effects. This gives an opportunity for multi-method modelling (MMM) to use all advantages of each method in combination.

Applying multi-method modelling techniques to model large infrastructure systems hasn't been properly researched yet, since the focus of most modellers has lien in increasing know-how on the singular methods themselves and additionally the computational power hasn't been that advanced in the past then it is nowadays to meet this challenge. Most literature focuses on comparing the available modelling method in their research area to find the best fitting [1] or discuss what the advantages and disadvantages are [2], but also how a model in one paradigm can be transformed into a model of another paradigm [3]. Especially under what circumstances, mathematically described, this is allowed.

But, as mentioned before, rather few publications try to combine the advantages of different modelling paradigms: System Dynamics (SD), a rather old approach, developed in the 1950s by Jay W. Forrester [4] has been researched very well [5].

Discrete Events Simulation (DES) [6] has been researched very well too. Literature on so-called hybrid models, where these two modelling paradigms are being combined, coupling continuous and discrete models, can be found [7].

When it comes to agent-based modelling (ABM), this being a rather new approach [8], modellers are still struggling with finding a 'right' definition – different definitions exist! [9] -, than thinking of how to combine for example agent-based methods with other modelling paradigms like System Dynamics. Researching literature revealed some works on first attempts and implementations where agent-based models are coupled with System Dynamics models [9] and one paper on a classification attempt for combining SD and ABM was found [10].

1 Aim and Goals

The aim of this dissertation project is to research different multi-method modelling techniques for modelling large socio-technical infrastructure systems as airports, to reveal their advantages and disadvantages and to give some guidance on how to apply these different modelling paradigms. Macro-based and micro-based modelling paradigms are different in view and offer different advantages. *The one modelling method's advantage is the other ones disadvantage. So why not combine their advantages?*

The focus will lie on ABM combined with SD and on DES combined with SD, since these two different modelling paradigms are a little bit trickier to combine. The use case where this will be tested is the Airport City, since this is a large, decomposable system and yields a lot of possibilities to apply multi-method modelling techniques.

2 Modelling Methods

Multi-method modelling with the following three modelling methods are researched and used in the application of airport planning, because these methods are, according to literature, used most often in this area and are also applicable to model the subsystem to answer specific research questions.



2.1 System Dynamics

In this macro-based modelling paradigm the point of view is from above, where only aggregated levels are looked at. It was developed in the 1950s by Jay W. Forrester, who applied it first in management systems [4]. He then transferred this methodology to social systems. Nowadays diverse literature on System Dynamics and Systems Thinking exists [5]. A SD model consists of six basic elements, as seen in table 1.

Element	Representation	Description
Stocks (Levels)	Stock	Describe the state of the system at each time and represent aggregates
Flows		Describe the changes of the stocks; are basically auxilia- ries and are only allowed between stocks and stocks and sinks/sources
Parameters	¢	Are constants and represent rates on which changes of stocks are dependent
Auxiliaries	0	Are helpful for a better un- derstanding of the model and represent algebraic equations
Sink/ Source	Ģ	Describe the boundaries of the system
Links		Describe the causalities of other elements

Table 1: Basic elements of System Dynamics.

A System Dynamics model basically represents a set of differential and algebraic equations. A simple example can be seen in Figure 1 and possible related equations in equations (1) and (2).



Figure 1: Simple stock and flow structure of SD.

Possible equation for time t:

$$\frac{d \, Stock(t)}{dt} = Flow \, (t) \tag{1}$$

$$Flow(t) = Stock(t) \cdot Parameter$$
(2)



The dynamics of the system emerge from causal links of the modelled variables that often form feedback loops. Such loops can be **balancing** or **reinforcing** driving the dynamics of the system.

Application areas are amongst others economics, health care and policy design.

2.2 Agent-based modelling

Agent-based modelling is a rather new approach and several properties of agents can be found in literature [9]. A selection of those is:

- **Proactiveness**, **purposefulness**: ability to take the initiative in order to achieve goals
- Situatedness: an agent is embedded in its environment and senses and acts on it
- **Reactiveness, responsiveness**: ability to react in a timely fashion to changes in the environment
- Autonomy: ability to interaction and communication with other agents, sometimes even awareness of other agents
- Anthromorphity: having human-like attributes like beliefes and intentions
- Learning: ability to increase performance over time based on previous experience
- Mobility: ability to move around in the simulated physical space, sometimes even between different machines
- **Specific purpose**: designed to accomplish well-defined tasks

Not every agent-based system has all of those properties [9] and depending on the agent's purpose one should not speak of agents and non-agents, but speak of a **continuum of agency**: The more agent characteristics an entity possess and the more developed those are, the higher the degree of agency it has.

2.3 Discrete events simulation

Discrete Events Simulation models are similar to agents, but the entity modelled here is not like an agent autonomous. It is passively led through the system instead. Furthermore, changes in the state of the system happen due to events at discrete points in time [11].

Between two consecutive events the state remains unchanged. Basic elements of DES are:

• Entities: have discrete properties and can be arranged in sets or lists

- Events: is an instantaneous happening that changes the state of the system. Events are arranged in an event list and are scheduled by using event notices that provide different information like tye or time of event.
- **Clock**: is a global variable that represents the simulated time. There are activities (time spans of certain length already know by simulation start) and delays (time spans of uncertain length like waiting time of a passenger in a queue). The clock can be forwarded in different manners.
- Scheduler: handels the event list, forwards the events to the event processing routine, also reschedules events if necessary and updates the clock.

This kind of modelling is mostly used in logistics and transportation.

3 Classification of MMM

Researching literature revealed that few attempts in multi-method modelling were done, but only one paper was found that tried to classify models that used ABM and SD modelling to model the whole system. There are three proposed categories [10].

Two coupled submodels are called **interfaced** if they have some point of interaction like communication between elements.

The submodels run alternating and independently (see Figure 2). There is no direct feedback between the submodels.



Figure 2: Interfaced multi-method model.

Two submodels are **sequential** if one submodel needs the output of another as input (see Figure 3).



Figure 3: Sequential multi-method model.

In an **integrated** multi-method model the submodels interact with each other in some way, as can be seen in Figure 4.



Figure 4: Integrated multi-method model.

According to Swinerd and McNaught [10] there are three ways to model an integrated design:

- Agents with rich internal structure: within each agent an SD model exists (see model on retail area). One can think of the SD model within an agent as the agent's 'brain' that 'tells' him what to do in a dynamic way. Here, influences from both sides can be considered: ABM submodel passes information to the SD submodel and vice versa.
- Stocked agents: a level within an SD model is used to bind an aggregate measure of an ABM. This could be an SD submodel that calculates production costs on car sales and the influence of fuel price on consumer choice of vehicle technology where consumers are modelled in the AB submodel. Here only influences from SD to ABM are modelled, but not the other way round.
- Parameters with emergent behaviour: a parameter of an SD model is calculated by an ABM. An example is an agent-based submodel where demographic development is modelled with agents together with their individual properties (age, sex, maybe socioeconomic factors). Out of these properties the value of a parameter for a coupled SD submodel is calculated.

There is a fine line between the classes of multimethod models. The modeller has to decide what fits best. It is also dependent on where the system boundaries lie. This classification approach is very useful as a starting point in researching multi-method modelling, since it is also applicable not only for SD and ABM modelling but also for other modelling methods.

4 Use Case: Airport City

The Airport City is a good example of a **large sociotechnical infrastructure system** to model, since on the one hand passenger demand forecasts predict an increase in the long term growth of transported passengers of avg. 4% per year [12] and on the other hand the system can be decomposed to smaller subsystems, that are somehow interconnected to each other on different levels. In Figure 5 a selection of important areas of the Airport City can be seen.



Figure 5: Selection of areas in the Airport City. (Source: adapted from company AI-MS Aviation Infrastructure Management Systems).

Also different views need to be satisfied here as well: planners, consumers, and stakeholders. A terminal model modelled with Discrete Events and a model of the retail area as an integrated ABM-SD model with rich internal structure has been developed. Furthermore, an agent-based model of the landside and the integration of a network-based agent-based model of the airside have been developed. Still planned is a SD model to calculate costs/profit and CO2 emission of airplanes and passenger demand forecasts. The advantages and disadvantages together with the possible coupling mechanisms are being researched. The described models are implemented in AnyLogic 7 [13].

4.1 Terminal model with discrete events

The terminal area is after the landside area the second area where departing passengers go to. The processes going on include check-in, security controls, passport controls and proceed to gate through retail area [14]. These processes are dependent on specific features of the passenger, like if he/she is business or tourist passenger (only hand luggage or not), or what his destination is (if within Schengen the passenger can proceed without passport control) or if he is handicapped or not. This submodel also includes transfer passengers, meaning passengers arriving at the airport by plane, going through passport control if necessary and proceeding to gate after going through retail area. This circumstance shows on the one hand, that this submodel gets input from the landside as well as from the airside and if some delays or other effects happen in the parts of the airport not represented in the terminal submodel it has an effect on the terminal submodel.

The research question in this model is if resources like personnel and number of open counters is enough at each time to maintain the quality standards measured in waiting time of passengers. This being a simple serverqueue question is modeled best using Discrete Events with counters and personnel being resources and passengers being entities. The DES model has already been implemented, as seen in Figure 6. This model includes the basic servers in such a process (check-in, security, passport control and transfer). In AnyLogic simple blocks for creating (sources), processing (server), and queuing (queue) entities are used. Resources are created via a (scheduled) resource pool.

Interfaces to possible coupled models like the adjacent landside model (not described here) are marked in orange. From an ABM-landside model agents enter the terminal system via an *Enter*-block. The agent based model modelling the landside can be coupled by this rule: every time an agent (passenger) exits the landside model, an entity (it is possible to pass other information as well) in the DES model is generated. Other interface from and to this terminal model are the connection to the retail area, transfer to the airside or if the flight was missed the exit to the landside to go back home.

4.2 Retail area with integrated ABM-SD model

The retail area is economically seen a very important part of the airport since most of the profit is gained here. The retail area is a shopping area after having passed the controls in the terminal where passengers go through when they proceed to the gate to depart.



Figure 6: Discrete Events Simulation of the Terminal.

One main research question in this area is to maximize profit by guaranteeing a specific level of quality for passengers like a short way to the gate or attractive sales. Here also spatial information is needed.

The processes are dependent on an individual's behaviour: he/she reacts to the environment and other passengers; therefore an ABM submodel that includes spatial information (map of the shops) is used.

The environment is the retail area with the shops. The inner parts of an agent should be dynamically changing, since this is more realistic: next to some individual parameters like age, economic status and gender as well as flight information, the agent consists of an SD submodel that models the need to eat and the need to buy other things.

In this case the retail area submodel is itself **an integrated model of agents with rich internal structure.** Each agent follows rules like:

- Proceed to gate in time
- If hungry and still in time to departure, then look for eating store and eat
- In dependence of attractiveness of store and in dependence of estimated income buy something if there is still time to departure and the need to buy something exceeds a specific threshold

These rules always take into account the by the SD model calculated need to buy something. This means there is communication from the SD module to the agent based module (tell him where to go). In return the need is dynamically calculated by the SD module by using individual information from the agent (age, gender, time until departure), but also using information from the environment of the AB module, like the attractiveness of the store that has some 'basic attractiveness' and furthermore is calculated by the number of people inside (if there are no people inside it may be something wrong with it, if there are too much people inside it is overcrowded).

A first version of this submodel has been developed (by M. Obermair and B. Glock), as seen in the 3D version of the animation in Figure 7. A network is applied to a ground floor and passenger agents interact on this plan with the shops trying to satisfy their goals that are modelled with SD, which can be seen in Figure 8.

Clearly, this multi-method approach allows agents to develop their needs dynamically and not by discrete rules, which gives a more realistic picture of the world.



Figure 7: Integrated multi-method model of retail area – agents with rich internal structure (agents).

To explore the disadvantages and advantages more specific, currently, a version of the retail area with single-method modelling approach is in development to have direct comparision. Therefore, measure variables are defined and compared.



Figure 8: Integrated multi-method model of retail area – agents with rich internal structure (SD model within each agent).

4.3 Airside

The airside of the airport is the part where diverse processes take place that deal with outgoing and incoming planes, like it is shown in Figure 9.

The so called ground handling processes include all processes around the plane. After touchdown (landing of the plane), the taxi arrives to get the passengers. After that the unloading and water refill starts. There are some limitations like cleaning and catering have to start after disembarking or fuelling after unloading luggage that need to be considered as well. In this submodel the spatial context plays an important role since travelling times contribute to quality measurements for passengers and the calculation of optimizations regarding the ground handling process itself.



Figure 9: Ground handling process [15].

The so called ground handling processes include all processes around the plane. After touchdown (landing of the plane), the taxi arrives to get the passengers. After that the unloading and water refill starts. There are some limitations like cleaning and catering have to start after disembarking or fuelling after unloading luggage that need to be considered as well.

In this submodel the spatial context plays an important role since travelling times contribute to quality measurements for passengers and the calculation of optimizations regarding the ground handling process itself.

The amount of flights is increasing and space on the airside where passengers can board (directly through the gate vie boarding bridges or on the apron) is limited. Therefore, in this case an AB submodel is used with a given network on which the agents can operate.

Different types of agents interact with each other on an environment like the network (selection):

- Planes
- Mobile stairs
- ♦ Catering vehicle
- Belt loader
- ♦ Baggage cart, ...

They have one overall goal to get the plane as soon as possible up in the air again.

4.4 Further submodels

Next a submodel modelling the landside with agents where the type of agents is different (cars, and not passengers) is in development and a submodel modelling the CO2 emission (with SD) as an integrated design is planned, where the agent-based and Discrete Event submodels have an influence on parameters of the SD model (classification of parameters with emergent behaviour) together with a single method approach of the retail area to compare differences directly.

5 The Big Modelling Picture

Summarizing the proposed submodels as seen in Figure 10 there is a terminal submodel with DES that interacts with the multi-method retail area submodel modelled with ABM, which itself is a multi-method model as the 'brain' of each agent is a SD model. The retail area submodel will be connected to the airside submodel. A submodel of the landside will be integrated.

Passengers proceed not only from landside to the airside, but also from airside to the landside, if they are arriving. Transfer passengers are included as well. So, we can see that those submodels are from integrated form all along, because these submodels have to exchange information (e.g. the agent or entity being passed on). The further planned SD submodel, calculating profit and CO2 emission requires information from the other submodels. Somehow, this SD model will give (delayed) some information back to the submodels (dotted lines in Figure 10), since the effect of the CO2 development will have an effect on the structures of the airport implemented with the submodels



Figure 10: The Coupling Schema of the Modelled and Planned Submodels.

SNE 26(3) – 9/2016 181

The advantages of this multi-method modelling tech-nique clearly are that the model gets more realistic by also including individual's properties. The disadvantage is that it can get more complex. On the other hand due to the modular architecture verification and validation will be, compared to a whole ABM model, easier.

6 Conclusions and Outlook

Using multi-method models is getting more and more important [16], since large infrastructure systems like airports get more complex and larger. Errors by using only one method for the large system can accumulate over time resulting in difficult decision making. By using different (best fitting) modelling methods for different subsystems and utilizing all their advantages a more realistic presentation of the model can be created. This also makes communication to decision makers easier and accumulating errors are eliminated to some extent. Furthermore, calculation times of the simulation models can be reduced as well.

Next (interesting) steps in this project include building and integrating a CO2-emission submodel and a profit calculation model that interact with the former described submodels and an airside and a landside model together with the comparison of the single method approach to the multi-method approach in the retail area.

Acknowledgement

This project is a dissertation within Talente funded by BMVIT Ministry of Transport, Innovation and Technology and handled by FFG Austrian research Promotion Agency.

References

- Scholl, HJ. Agent-Based and System Dynamics Modelling: A Call for Cross Study and Joint Research. In Proceedings of the 34th Annual Hawaii International Conference on System Dynamics; 2001; Hawaii, USA.
- [2] Lorenz T, Jost A. Towards an Orientation Framework in Multi-Paradigm Modelling. In Proceedings of the 24th International Conference of the System Dynamics Society; 2006; Nijmegen, The Netherlands.

- [3] Einzinger P. A Comparative Analysis of Sys-tem Dynamics and Agent-Based Modelling for Health Care Reimbursement Systems. Dissertation, TU Wien, Austria; 2014.
- [4] Forrester J. Industrial Dynamics. Productivity Press, Cambridge, MA, 1961.
- [5] Sterman J. Business Dynamics Systems Thinking and Modelling for a Complex World. McGraw-Hill Education Ltd, USA, 2000.
- [6] Banks J, Carson J. Discrete-Event System Simulation. Prentice-Hall Inc., Englewood Cliffs, New Jersey, 1984.
- [7] Jovanoski B, Minovski R, Voessner S, Lichtenegger G. Combining System Dynamics and Discrete Event Simulations – Overview of Hybrid Simulation Models. 2012.
- [8] Macal C, North M. Tutorial on Agent-Based Modelling and Simulation Part 2: How to Model with Agents. In Proceedings of the 2006 Winter Simulation Conference; 2006; Monterey, California.73-83.
- [9] Schieritz N, Milling P. Modelling the Forest of Modelling the Trees – A Comparison of System Dynamics and Agent-Based Simulation. In Proceedings of the 21st International Conference of the System Dynamics Society; 2003; New York City, USA. 1-15.
- [10] Swinerd C, McNaught K. Design Classes for Hybrid Simulations Involving Agent-Based and System Dynamics Models. *Elsevier Simulation Modelling Practice and Theory*; 2012.118-133.
- [11] Zeigler B, Praehofer H, Kim T. Theory of Modelling and Simulation: Integrating Discrete Event and Continuous Complex Dynamic Simulation. Academic Press: San Diego; 2000.
- [12] De. Neufville R, Odoni A. Airport Systems Planning, Design and Management. 2nd Edition, United States, The McGraw-Hill Education LLC; 2013.
- [13] AnyLogic. www.anylogic.com. Accessed: 2015.
- [14] Schulz A, Baumann S, Wiedenmann S. Flughafen Management. Oldenburg Verlag, München; 2010.
- [15] Norin A. Airport Logistics A Case Study of the Turn-Around Process. *Elsevier Journal of Air Transport Man*agement; 2012. 31-34.
- [16] Brailsford S, Mustafee N, Diallo S, Padilla J, Tolk A. Hybrid Simulation Studies and Hybrid Simulation Systems: Definitions, Challenges, and Benefits. *In Proceedings of the 2015 Winter Simulation Conference*; 2015; Huntington Beach, California. 1678-1692.